

## sat-nms ACU-RMU-3 - Rack Mount Unit Antenna Controller

The **sat-nms** ACU-RMU-3 is a complete and compact 6RU 19" rack-mount chassis antenna controller with optional high performance tracking. It can be used as a cost-efficient antenna position controller or as a full featured antenna step-track system. The system is based on the **sat-nms** ACU-ODM Outdoor Module and includes three motor-driver units. All interfaces to the satellite ground station antenna are accessible via the rear panel of the 19" chassis with direct connection to the frequency inverters and modules.

The **sat-nms** ACU-RMU-3 can not only be used to point your antenna precisely to the satellite but also with the option to perform highly accurate step-tracking, adaptive tracking including orbit prediction.

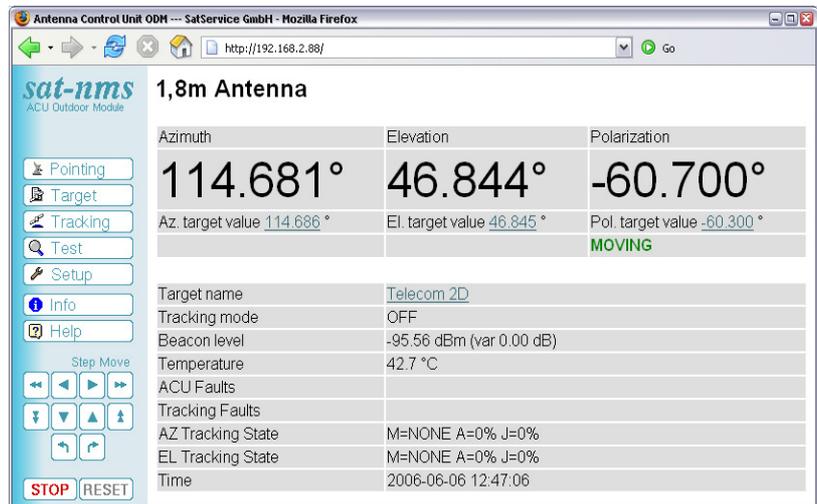
The **sat-nms** ACU-RMU-3 includes:

- Three independent and flexible motor-drive interfaces, allowing simultaneous driving of all 3 axes with 3-phase frequency inverters (Az. and El.) up to 3kW (larger power available in other mechanical configurations) and solid state relays (Pol.)



- Direct Ethernet UDP Interface for **sat-nms** LBRX Beacon Receiver
- Analog Voltage Interface for 3<sup>rd</sup> party Beacon Receivers
- Resolver analog Angle Detectors Interface measuring Azimuth, Elevation and Polarization
- Optical SSI Interface high precision digital Angle Detectors as Alternative
- Analog ADC Interface to measure the Voltage across a precision Potentiometer also available

The **sat-nms** ACU-RMU-3 Unit includes an integrated web server and provides its operator interface via web browser. The **sat-nms** ACU-RMU-3 includes also http and ftp for remote diagnosis and support. The system is easy to maintain. All support can be performed remotely and the interface to high-level MNC Systems is provided via Ethernet, TCP/IP, SNMP and RS232.



Antenna Control Unit ODM --- SatService GmbH - Mozilla Firefox  
http://192.168.2.88/

**sat-nms** ACU Outdoor Module

1,8m Antenna

Azimuth	Elevation	Polarization
114.681°	46.844°	-60.700°
Az. target value 114.686°	El. target value 46.845°	Pol. target value -60.300°
MOVING		

Target name	Telecom 2D
Tracking mode	OFF
Beacon level	-95.56 dBm (var 0.00 dB)
Temperature	42.7 °C
ACU Faults	
Tracking Faults	
AZ Tracking State	M=NONE A=0% J=0%
EL Tracking State	M=NONE A=0% J=0%
Time	2006-06-06 12:47:06

Navigation: Pointing, Target, Tracking, Test, Setup, Info, Help, Step Move, STOP, RESET

### Key Features

- Web-based, user-friendly Operator Interface
- Step-track and Adaptive Tracking
- Very compact 6RU 19" rack-mount Design
- Integrated 3-phase Frequency Inverters
- HTTP and SNMP for external MNC Interface

### Contact Information

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## Technical Specification

### Positioning

Operational Modes <b>sat-nms</b> ACU-RMU-3	Manual Mode, Positioner
Operational Modes <b>sat-nms</b> ACU-RMU-3T	Manual Mode, Positioner, Step Track, Adaptive Tracking, Program Track.
Position Encoding	Resolver, Optical Digital SSI and Potentiometer, scalable per Axis
Quantization Error	Resolver 16bit: 0.0055° SSI: 13bit: 0.044°, 16bit: 0.0055°, 17bit: 0.0028°, 19bit: 0.0007°
Display Position Resolution	0.001°
Maximum Travel Rate of each Antenna Axis	1°/sec
Interfaces to Beacon Receivers	<b>sat-nms</b> LBRX or analog Voltage Input for other Vendors Equipment
Analog Voltage Input	0 to 10V
Option Tracking Accuracy	Encoder coupling and alignment error should not exceed 0.003° to achieve specified tracking accuracy. The influence of antenna structure thermal error is not considered.
In step-track Mode	Better than 10% of Receive 3dB Beamwidth (RMS).
In smoothing tracking Mode	Better than 5% of Receive 3dB Beamwidth (RMS).
Position Encoding	1 LSB of Resolver / Digital Conversion
Operational Modes	Manual Mode, Step Track, Adaptive Tracking takes into account last Days History, Program Tracking based on time stamped File Data
Number of Presets	99 Storage of <b>sat-nms</b> ACU Configuration (including <b>sat-nms</b> LBRX Beacon Receiver Settings)

### System Interfaces

<b>sat-nms</b> MNC Interface	10-Base-T, via HTTP GET Requests, RS232 and SNMP
Operator Access	With Web Browser
To <b>sat-nms</b> MNC and <b>sat-nms</b> ACU-IDU	Ethernet RJ45 or RS232 / Mini Combicon MCV1.5/XX-G-3.5
To 6 Limit Switches	Opto-Coupler Input for Azimuth, Elevation and Polarization / Screw Terminal
Interlock and motors-off Switches	Opto-Coupler Input / Screw Terminal
3 angular Detectors	Resolver, SSI or A/D Input / Mini Combicon MCV1.5/XX-G-3.5
Motor Driver Interface	Via Opto-Coupler In- and Outputs: Motor on/off and direction, low and high Speed Selection, Reset Driver, Driver Fault
(For Frequency Inverter, DC servos etc.)	
Motor Interface	Direct at Frequency Inverters with shielded cable up to 3kW (AZ/EL) and up to 0.75kW (Pol). Optional solid-state-relays for Pol-Motor with RC-Combo.

### Electrical and Mechanical Specification, Environmental Conditions

Supply Voltage	380VAC Mains Voltage 3 phase
Power Consumption	100W + Motor Power
Temperature Range	-10° to 50°C
Humidity	Up to 90% non-condensing
Dimensions	19", 6RU, 450x270x380 mm (WxHxD)



**Antenna Setup Parameters**

General			
Note	1.8m Antenna	Date / time	2006-06-06 13:...
Axes control mode	PARALLEL	RS485 address	A
Azimuth			
AZ Antenna diameter	1.8 m	Az. step delta	0.020 °
AZ Position sensor type	RESOLVER	AZ Motor driver type	DIR-START
AZ Calibration offset	0.000 °	AZ Low speed threshold	1.0 °
AZ Calibration scale	0.000000	AZ Pointing hysteresis	0.100 °
AZ Sense invert	NORMAL	AZ Motor timeout	20000 msec
AZ Lower limit	100.000 °	AZ Upper limit	300.000 °
Elevation			
EL Antenna diameter	1.8 m	EL step delta	0.020 °
EL Position sensor type	RESOLVER	EL Motor driver type	DIR-START
EL Calibration offset	35.000 °	EL Low speed threshold	1.0 °
EL Calibration scale	0.120000	EL Pointing hysteresis	0.080 °
EL Sense invert	NORMAL	EL Motor timeout	20000 msec
EL Lower limit	0.000 °	EL Upper limit	90.000 °
Polarization			
Pol Antenna diameter	1.8 m	Pol step delta	0.020 °
Pol Position sensor type	RESOLVER	Pol Motor driver type	DIR-START
Pol Calibration offset	0.000 °	Pol Low speed threshold	1.0 °
Pol Calibration scale	0.000000	Pol Pointing hysteresis	0.100 °
Pol Sense invert	NORMAL	Pol Motor timeout	20000 msec
Pol Lower limit	0.000 °	Pol Upper limit	300.000 °